

# The **blockdiagram** package

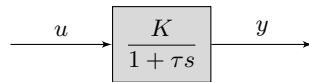
Guillaume J. Laurent

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The **blockdiagram** package is a set of tikz macros to draw nice block diagrams.

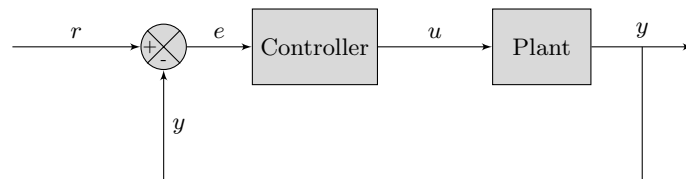
## 1 Transfer function

```
\begin{tikzpicture}
  \inputnode{I}
  \blockr{I}{G}{\frac{K}{1+\tau s}}
  \link{I}{G}{u}
  \outputnode{G}{O}
  \link{G}{O}{y}
\end{tikzpicture}
```



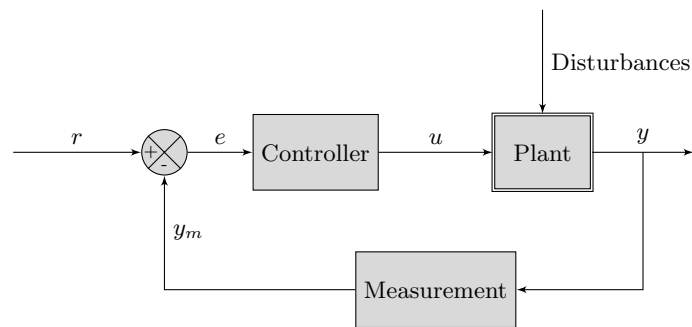
## 2 Feedback Loop

```
\begin{tikzpicture}
  \inputnode{I}
  \sumblockr{I}{S}{+}{-}{}
  \link{I}{S}{r}
  \blockr{S}{C}{Controller}
  \link{S}{C}{e}
  \blockr[3cm]{C}{P}{Plant}
  \link{C}{P}{u}
  \outputnode{P}{O}
  \link{P}{O}{y}
  \xylink{P-O}{S}{y}
\end{tikzpicture}
```



### 3 Another Feedback Loop

```
\begin{tikzpicture}
  \inputnode{I}
  \sumblockr{I}{S}{{+}}{-}{}
  \link{I}{S}{$r$}
  \blockr{S}{C}{Controller}
  \link{S}{C}{$e$}
  \plantblockr[3cm]{C}{P}{Plant}
  \link{C}{P}{$u$}
  \nodea{P}{D}
  \ylink{D}{P}{Disturbances}
  \outputnode{P}{O}
  \link{P}{O}{$y$}
  \blockb{C-P}{M}{Measurement}
  \yxlink{P-O}{M}{}
  \xylink{M}{S}{$y_m$}
\end{tikzpicture}
```



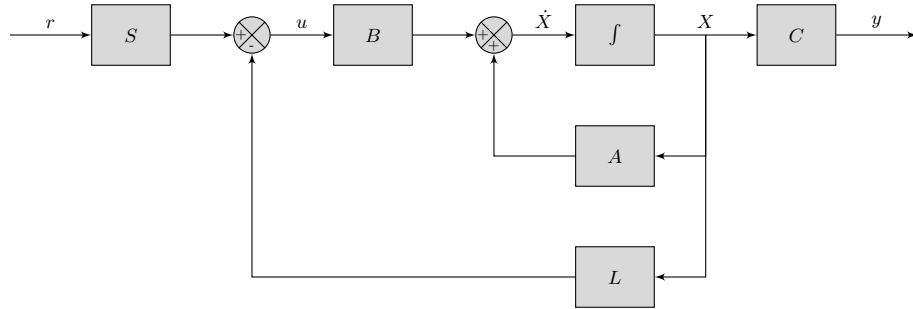
### 4 Linear Quadratic Regulator

```
\begin{tikzpicture}\setdiagramscale{0.8}
  \inputnode{E}
  \blockr{E}{filter}{$S$}
  \link{E}{filter}{$r$}
  \sumblockr{filter}{sum2}{{+}}{-}{}
  \link{filter}{sum2}{}
  \blockr{sum2}{command}{$B$}
  \link{sum2}{command}{$u$}
  \sumblockr{command}{sum1}{{+}}{+}{}
  \link{command}{sum1}{}
  \blockr{sum1}{integrator}{$\int$}
  \link{sum1}{integrator}{$\dot{X}$}
  \blockr[3cm]{integrator}{obs}{$C$}
  \link{integrator}{obs}{$X$}
  \outputnode{obs}{S}
  \link{obs}{S}{$y$}
  \blockb{integrator}{evolution}{$A$}
  \yxlink{integrator-obs}{evolution}{}
  \xylink{evolution}{sum1}{}
  \blockb{evolution}{regulator}{$L$}
```

```

\ymlink{integrator-obs}{regulator}{}
\xylink{regulator}{sum2}{}
\end{tikzpicture}

```



## 5 Observer

```

\begin{tikzpicture}
\inputnode{E}
\plantblockr{E}{system}{Plant}
\outputnode{system}{S}
\link{E}{system}{$u$}
\link{system}{S}{$y$}
\noder[1cm]{S}{SS}
\blockb{SS}{observer}{Observer}
\ymlink{system-S}{observer.170}{}
\ymlink{E-system}{observer.190}{}
\noder{observer}{X}
\link{observer}{X}{$\hat{X}$}
\end{tikzpicture}

```

